LEAD FREE

RoHS COMPLIANT

HEC-4xxx-E-R Harsh Environment Controller

Covered Models:

HEC-4000-E-R	HEC-4011-E-R	HEC-4102-E-R	HEC-4113-E-R	HEC-4204-E-R
HEC-4001-E-R	HEC-4012-E-R	HEC-4103-E-R	HEC-4114-E-R	HEC-4210-E-R
HEC-4002-E-R	HEC-4013-E-R	HEC-4104-E-R	HEC-4200-E-R	HEC-4211-E-R
HEC-4003-E-R	HEC-4014-E-R	HEC-4110-E-R	HEC-4201-E-R	HEC-4212-E-R
HEC-4004-E-R	HEC-4100-E-R	HEC-4111-E-R	HEC-4202-E-R	HEC-4213-E-R
HEC-4010-E-R	HEC-4101-E-R	HEC-4112-E-R	HEC-4203-E-R	HEC-4214-E-R

Manual Contents

Getting Started

HEC-4xxx-E-R Features

WARNING!!

The **HEC-4xxx-E-R,** as with other programmable controllers must not be used alone in applications which could be hazardous to personnel in the event of failure of this device. Precautions must be taken by the user to provide mechanical and/or electrical safeguards external to this device. This device is **NOT APPROVED** for domestic or human medical use.

Getting Started

This section explains how to read this manual and understand the symbols and information that it contains.

To begin using your HEC Controller, you will need to follow these steps:

- Install EZ LADDER Toolkit if not already installed (not included).
- Configure the HEC Controller in the EZ LADDER Toolkit Project Settings.
- Using purchased or self-made cables, connect the Input Power and Programming Port.
- Write a ladder diagram program.
- Download and run the program on the HEC Controller.

Refer to the appropriate sections of this manual for details on the above items.

How to Use this Manual

In this manual, the following conventions are used to distinguish elements of text:

BOLD   Denotes labeling, commands, and literal portions of syntax that must appear exactly as shown.

italic   Used for variables and placeholders that represent the type of text to be entered by the user.

SMALL CAPS   Used to show key sequences or actual buttons, such as OK, where the user clicks the OK button.

In addition, the following symbols appear periodically in the left margin to call the readers attention to specific details in the text:

Warns the reader of a potential danger or hazard associated with certain actions.

Appears when the text contains a tip that is especially useful.

Indicates the text contains information to which the reader should pay particularly close attention.

All Specifications and Information Subject to Change without Notice

Configuring the HEC-4xxx-E-R Target in EZ LADDER Toolkit

Before you can program and use the HEC Controller, it must be configured as a target within the EZ LADDER Toolkit. For help with installing or using EZ LADDER, please refer to the EZ LADDER User's Manual.

1. In EZ LADDER, from the File Menu at the top, click **PROJECT** then **SETTINGS**. This will open the Project Settings Window. Select **HEC-4000** as the target from the choices. Refer to Figure 1.1.
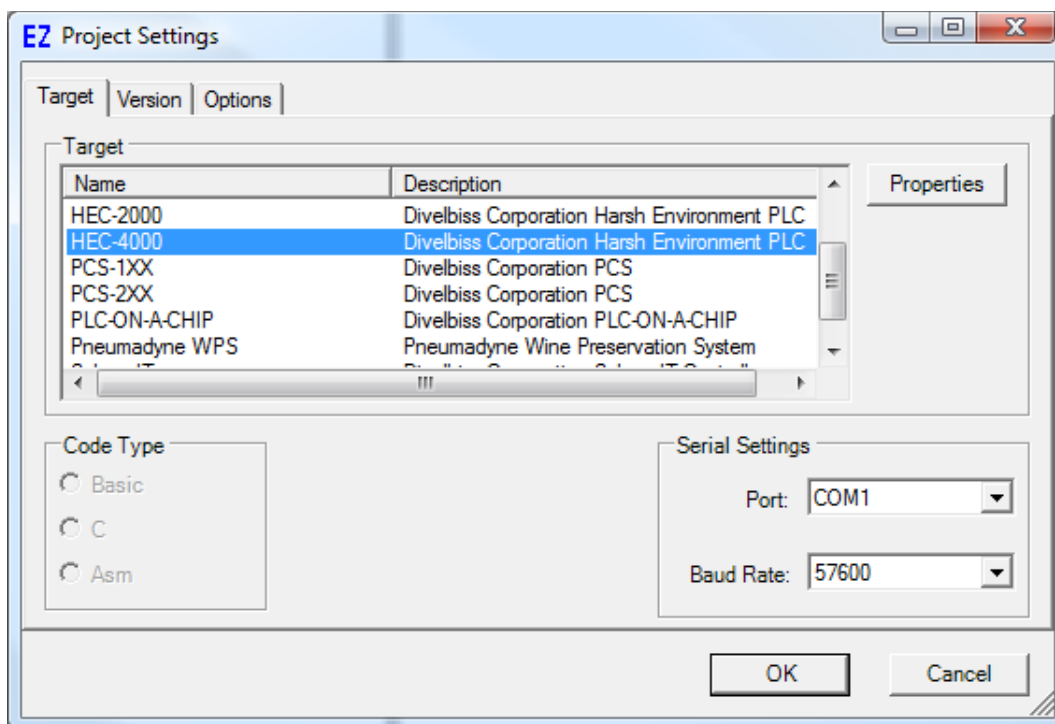

Figure 1.1 - Project Settings Window

2. Click **OK**. A new window will open. Select the Model number of the HEC-4xxx from the drop-down menu. Click **OK**. This will close the Project Settings Window, saving the HEC-4xxx as the target for this ladder diagram project. The E-R suffix is for RoHS and should be ignored when selecting targets.

Loading the HEC-4xxx-E-R Kernel

THE HEC-4XXX-E-R WILL NOT FUNCTION UNLESS THIS STEP (KERNEL LOADING) IS COMPLETED.

The kernel is the firmware for the controller and to provide greater flexibility and reliability, HEC Controller shipments are factory shipped **without** a kernel. If this is a new unit from the factory, it will be necessary to load the kernel before a ladder program can be downloaded.   If the kernel is already loaded, this step is not required. To upgrade a kernel, see the EZ LADDER User's Manual.

To install the HEC-4xxx-E-R's kernel:

1. Verify the target has been configured (see *Configuring the HEC-4xxx-E-R Target in EZ LADDER Toolkit*).

2. Connect the Programming cable(s) from the computer to the HEC-4xxx-E-R. See *Programming Port* in the *HEC-4xxx-E-R Features* section.

3. Create a small one-rung program with a normally open (direct contact) and an output tied together. You may also open a pre-existing program for the HEC. EZ LADDER version 1.0.4.4 and later includes a sub-directory (...EZ LADDER\Kernel Install Start Programs\)which has starter programs for each target to load the kernel. Choose *GetStarted_HEC-4XXX.dld*.

4. Click the **C** (Compile) button

5. Click the **MON** (Monitor) button to change from the 'Edit' to 'Monitor' Mode.

6. Click the (Connect) button to connect to the target. A dialog will appear automatically when no kernel is loaded. If this dialog does not appear, click **PROJECT** then **BOOTLOADER**.

7. Click the **BROWSE** button and select the target's kernel (by partnumber) located by default at C:\Program Files\EZ Ladder\Kernel\

The following are kernel names and descriptions:

File Name	Description	To be Used on (Partnumber)
HEC_4000.dat	Kernel for HEC-4xxx-E-R	HEC-4000-E-R, HEC-4001-E-R, HEC-4002-E-R, HEC-4003-E-R, HEC-4004-E-R, HEC-4010-E-R, HEC-4011-E-R, HEC-4012-E-R, HEC-4013-E-R, HEC-4014-E-R, HEC-4100-E-R, HEC-4101-E-R, HEC-4102-E-R, HEC-4103-E-R, HEC-4104-E-R, HEC-4110-E-R, HEC-4111-E-R, HEC-4112-E-R, HEC-4113-E-R, HEC-4114-E-R, HEC-4200-E-R, HEC-4201-E-R, HEC-4202-E-R, HEC-4203-E-R, HEC-4204-E-R, HEC-4210-E-R, HEC-4211-E-R, HEC-4212-E-R, HEC-4213-E-R, HEC-4214-E-R
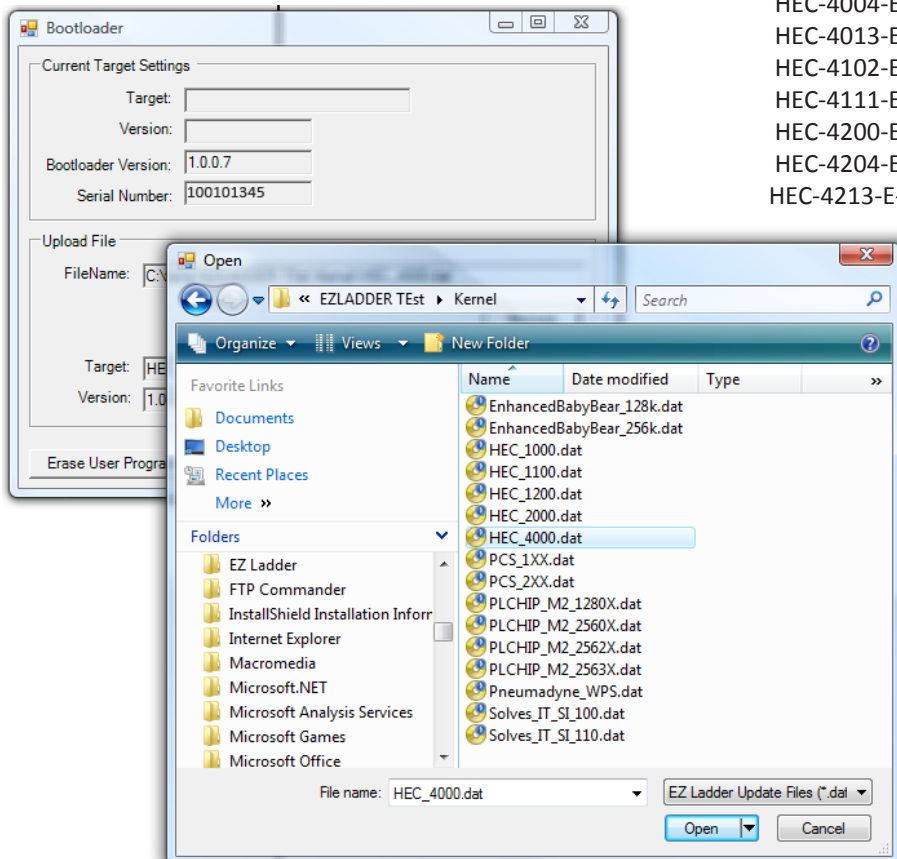
8. Click the **OPEN** button to finish the kernel selection. Make sure the correct kernel is chosen.

9. Click the **UPDATE TARGET** button to install the kernel.
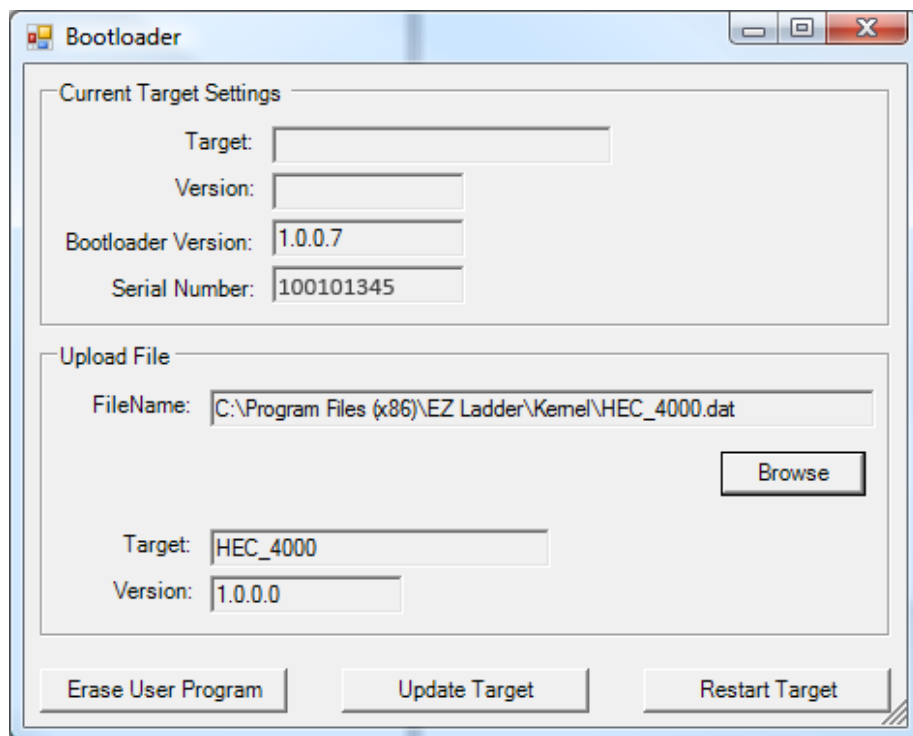
10. A dialog box will appear to show the status of the kernel installation. This could take a couple of minutes to install.

11. When the dialog windows close, the installation is complete. The HEC is ready to use and may be connected to and programs may be downloaded.

The HEC-4xxx Serial Number is factory set and cannot be changed.

Getting to Know the HEC-4xxx-E-R

The HEC-4xxx-E-R Controller is designed to provide powerful programmable features in a tough, harsh environment resistant package. The main features of the HEC-4xxx-E-R are accessed via sealed Deutsch connectors that will be referred to as the 'A' connector which is grey and the 'B' connector which is black.

Refer to Figure 1.2, as it illustrates the HEC-4xxx-E-R.
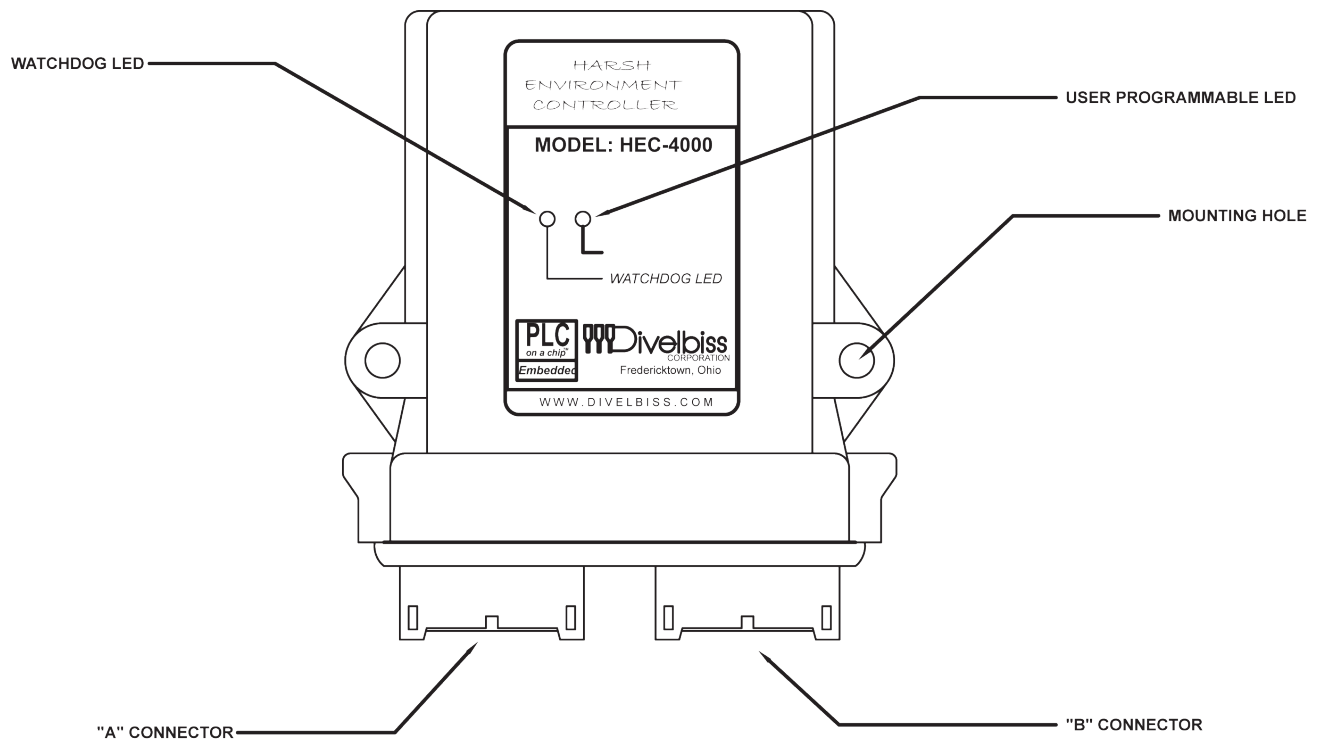
Figure 1.2 - HEC-400x-E-R Product Drawing

Each HEC connector is a Deutsch sealed connector with 12 connections each.

The mating connectors for the HEC's connectors is sold separately. Connectors may be purchased as kits or cable assemblies may be purchases with the mating connectors pre-wired with flying leads on one end.

In addition to connectors and kits for standard wiring, several programming break-out cable assemblies may be purchased.

Refer to Figure 1.3 for the HEC-4xxx-E-R A and B connector front view Pin Assignments.
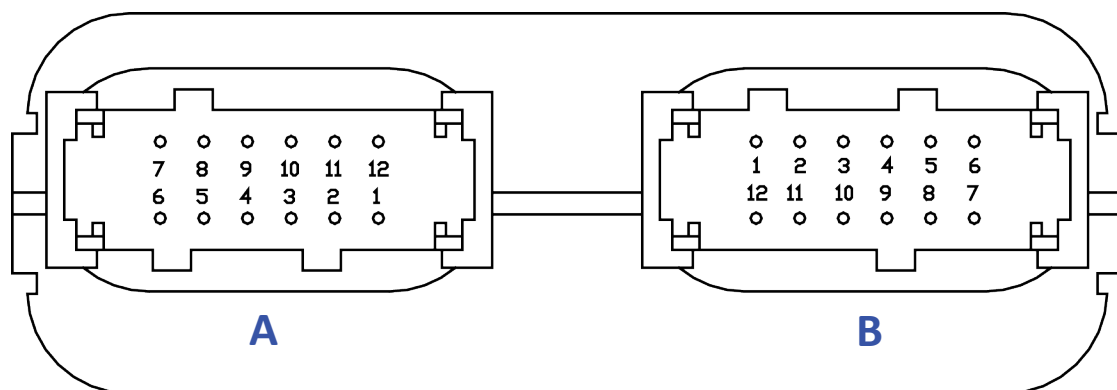
Figure 1.3 - HEC-400x-E-R A / B Connector Front View

A and B Connector Pin Functions

CONNECTOR 'A' (GRAY)		CONNECTOR 'B' (BLACK)	
Pin 1	CAN 0 Hi	Pin 1	Output 0 / PWM 1 (GPO0/PWM1)
Pin 2	CAN 0 Low	Pin 2	Output 1 / PWM 3 (GPO1/PWM3)
Pin 3	CAN 1 Hi	Pin 3	Output 2 / PWM 5 (GPO2/PWM5)
Pin 4	CAN 1 Low	Pin 4	Output 3 / PWM 7 (GPO3/PWM7)
Pin 5	Programming Port TX	Pin 5	Output 4 (GPO4)
Pin 6	Programming Port RX	Pin 6	Output 5 (GPO5)
Pin 7	+VDC Input Power	Pin 7	Input 0 / CNTR 1 (GPI0/CNTR0)
Pin 8	+VDC Input Power	Pin 8	Input 1 / CNTR 2 (GPI1/CNTR1)
Pin 9	+VDC Input Power	Pin 9	Input 2 (GPI2)
Pin 10	-DC / Input Power Common	Pin 10	Input 3 (GPI3)
Pin 11	Analog Input 0	Pin 11	Analog Input 2
Pin 12	Analog Input 1	Pin 12	Analog Input 3

Assembling / Dis-Assembling the HEC-4xxx-E-R

To dis-assemble the HEC Controller you will need a flat-head screwdriver.

1. Place the screwdriver as shown, press in on the locking latch (of the connector assembly) and push forward gently simultaneously to slide the locking latch out of the enclosure .

2. Repeat this for the second side and slide the entire connector assembly with the printed circuit board out of the enclosure.

Push at Angle shown   Flat-End Screwdriver

Push Latches each side with screwdriver & Slide Out

Push at Angle shown

Detail of Locking Latch   **Push Latch**
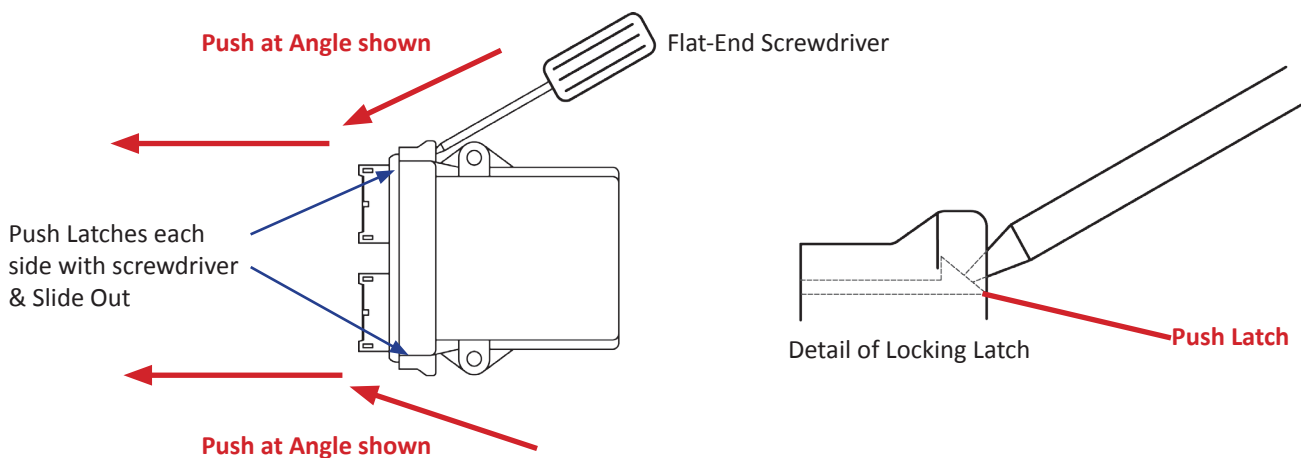
To assemble the HEC Controller:

1. Align the connector assembly with printed circuit board into the enclosure. The printed circuit board wil align with the slots in the enclosure.

2. Slide the assembly completely into the enclosure until the locking latches are secure. Please note: If the HEC controller has an optional serial port, make sure the serial board wires do not interfere or get caught on the enclosure's LED pipes (clear plastic tubes).

HEC-4xxx-E-R Features

This section explains the Harsh Environment Controller (HEC-4xxx) hardware features, options and information regarding EZ LADDER Toolkit for basic operation.

Programming Port

The HEC-4xxx-E-R is programmed using its Programming Port (COM 0). This RS232 serial port is only to be used for programming using Divelbiss EZ LADDER Toolkit software. This is not a general purpose port and may not be used in any other capacity than programming the controller itself.
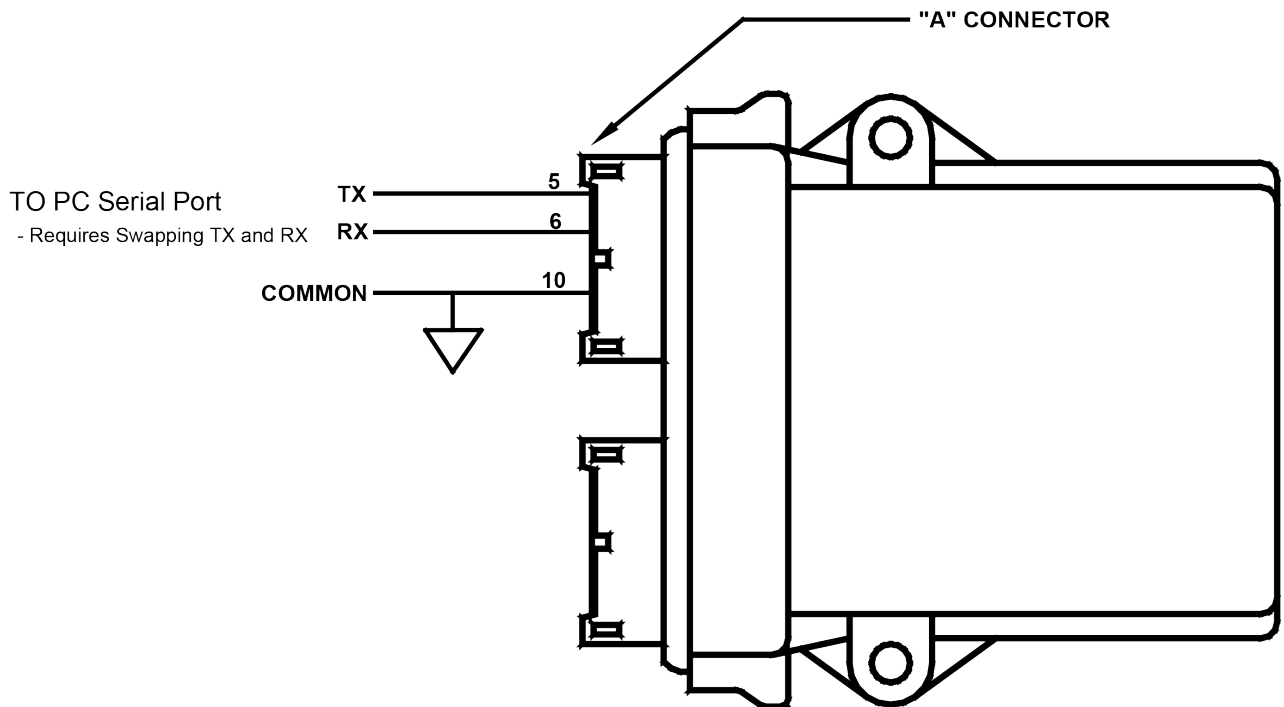
The Programming Port defaults to:	Baud:	57600
	Parity:	None
	Data Bits:	8
	Stop Bits :	1

The HEC-4xxx-E-R Programming Port is wired through the A Connector. The Programming Port requires a NULL MODEM cable or connection to the computer to establish communications between EZ LADDER Toolkit and the HEC Controller.

This connection may be made by manufacturing your own programming cable. The mating connector for the HEC-4xxx-E-R Programming Port may be purchased as a kits (HEC-10, Requires special Crimp Tool) or a complete pre-wired assembly for the A Connector (HEC-100). Ideally, the best option is to purchase the HEC-910 Breakout Cable Assembly. This cable assembly connects in-line with all connected devices and provides an RS232 9-pin D Male connector as the interface. This also requires a null modem cable (ICM-CA-34) that connects from the HEC-910 to the computer serial port. While this is the most commonly used program-ming cable set, other programming cable set options are available.

Refer to Figure 2.1 for Direct Connections and Figure 2.2 for the HEC-900 Break-out method.

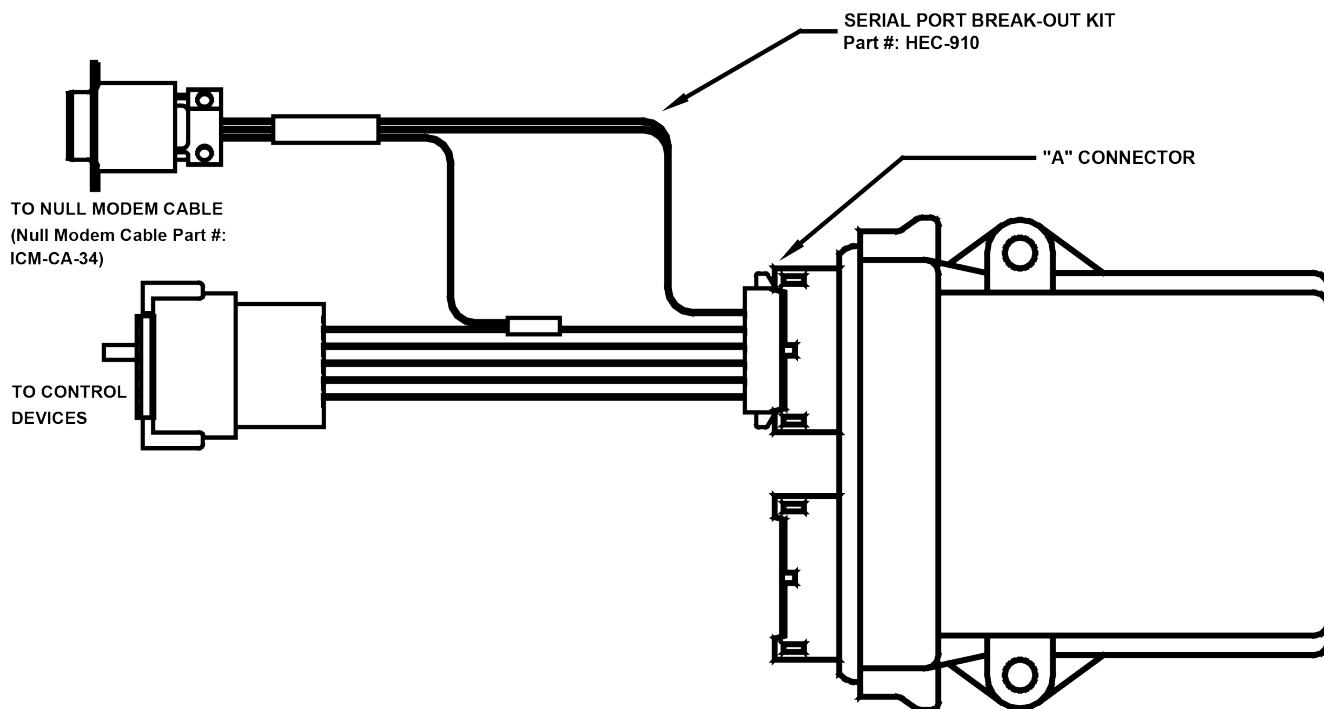**Figure 2.1 - Programming Port Direct Connection**

SERIAL PORT BREAK-OUT KIT
Part #: HEC-910

"A" CONNECTOR

TO NULL MODEM CABLE
(Null Modem Cable Part #:
ICM-CA-34)

TO CONTROL
DEVICES

Figure 2.2 - Programming Port Break-out Connections

Watchdog LED

The operating status of the HEC-4xxx-E-R can be determined the by Watchdog LED. When the Watchdog LED is flashing at a slow rate, approximately once per second, then there is no ladder program executing. When the Watchdog LED is flashing at a fast rate (several times per second), a program has been loaded and it is executing.

Should the Watchdog LED not flash at all, first check the input power. If the input power is correct and there is still no Watchdog LED, contact Divelbiss Technical Services.

Status LED

The HEC-4xxx-E-R provides a programmable status LED that can be seen from the front of the unit. This LED is programmed in the ladder diagram by using the STATUS variable that is automatically created when the target is selected.

Input Power

The HEC-4xxx-E-R may be powered using 8-32VDC. The input power must be of sufficient supply to drive the HEC controller and all the digital outputs (based on the load currents for each). Due to wire size limitations of the HEC-4xxx-E-R connectors, multiple input power pins are provided to allow for *parallel* input power lines to increase the amount of current (for heavier output loads). For an input power wiring diagram, refer to Figure 2.3.

"A" CONNECTOR

3 Input Power Connections in
Parallel for increased current.
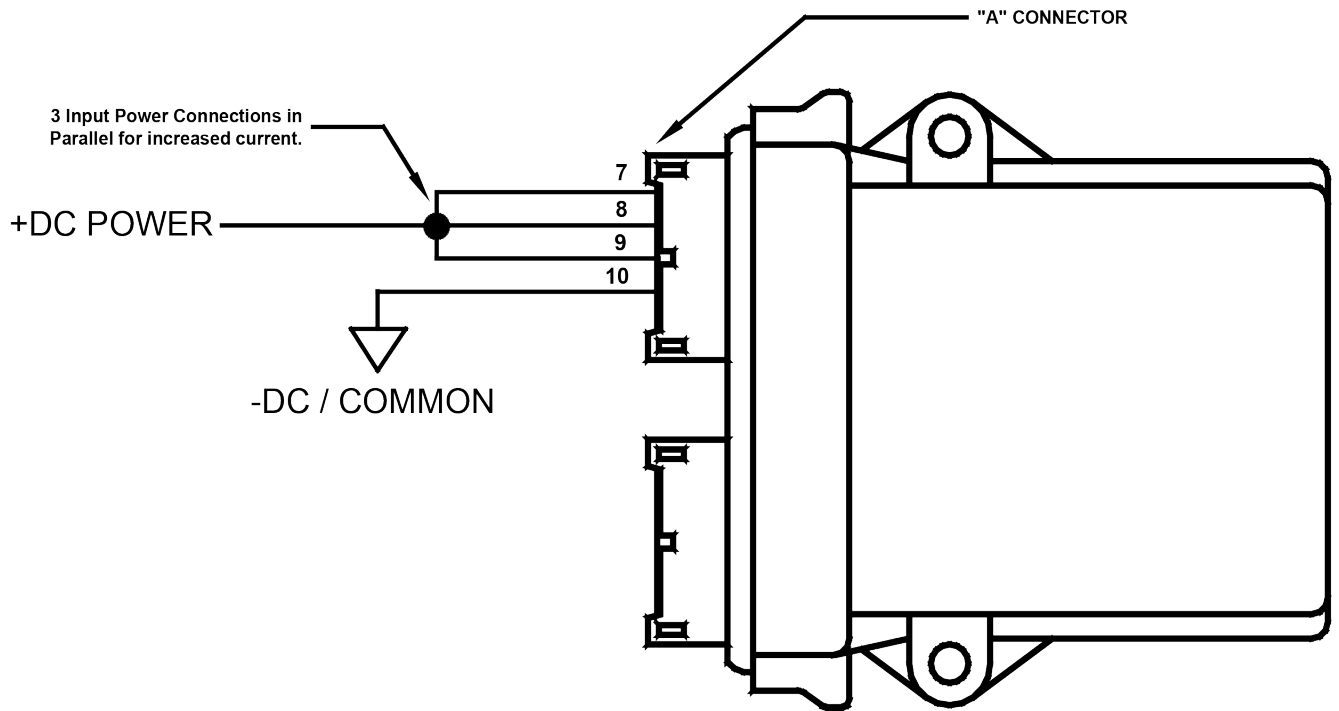
+DC POWER

7
8
9
10

-DC / COMMON

Figure 2.3 - Input Power Connections

Mounting

The HEC-4xxx-E-R mounts simply using two mounting screws.   The HEC can easily accept mounting screws up to 1/4" in diameter.

1.4370

5.2374
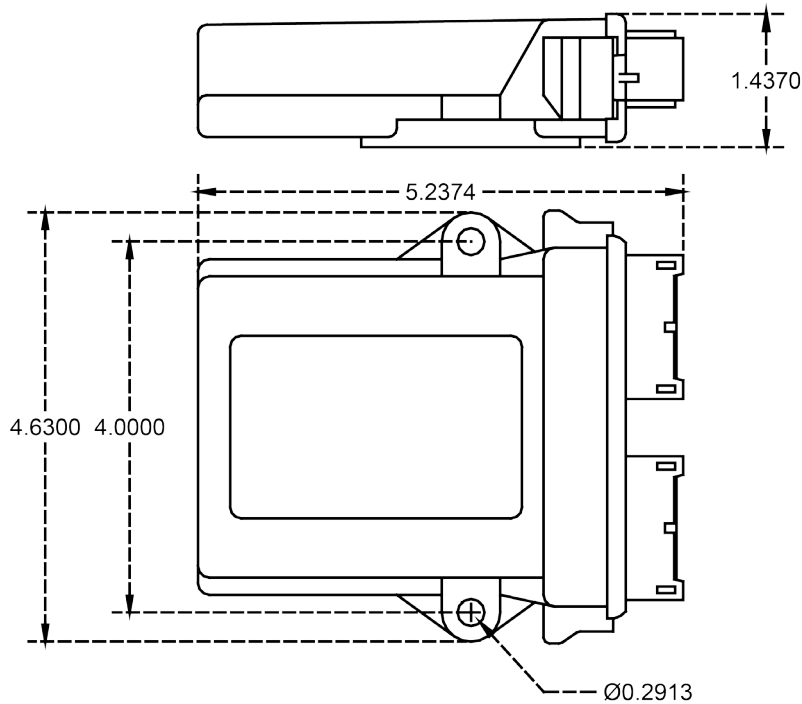
4.6300 4.0000

Ø0.2913

Figure 2.4 - HEC-4xxx-E-R Mounting

Digital Inputs

The HEC-4xxx-E-R includes 4 on-board digital inputs. They are identified in EZ LADDER Toolkit and this manual as GPI0 through GPI3. Each digital input can accept an input voltage of 8-32 VDC. The presence of this voltage on an input will result in the input being read as TRUE in the ladder diagram.

GPI0 and GPI1 may be used as general purpose digital inputs or high speed counters; while GPI2 - GPI3 can only be used as general purpose digital inputs. For information on using GPI0 or GPI1 as high speed counter inputs, refer the COUNTER INPUTS Section of this User's Manual.

To read a digital input status in a ladder diagram, place and connect the appropriate contact for your needs. The DIRECT CONTACT and INVERTED CONTACT functions are used to read digital inputs in the ladder diagram. When placing the contact, verify you select the correct input address (GPI0 - GPI3) from the provided drop-down menu.

As GPI0 and GPI1 are dual function inputs that operate as digital inputs or high speed counter inputs, each input has a debounce circuit that can be enabled or disabled. The debounce circuit is disabled by default as if the inputs were to be used as high speed counters. If using GPIO or GPI1 as a standard digital input, the debounce circuit should be enabled. To enable the debounce circuit, a variable for each is automatically created D_GPI0 and D_GPI1 respectively. To use these variables, assign them as a direct coil in the ladder diagram. When true, the debounce for the circuit is enabled.

It is important that the input device source be the same as the HEC-4xxx input power source as shown. Separate power sources could result in a damage to the controller if input power is lost, but the inputs are still powered. Refer to Figure 2.5.
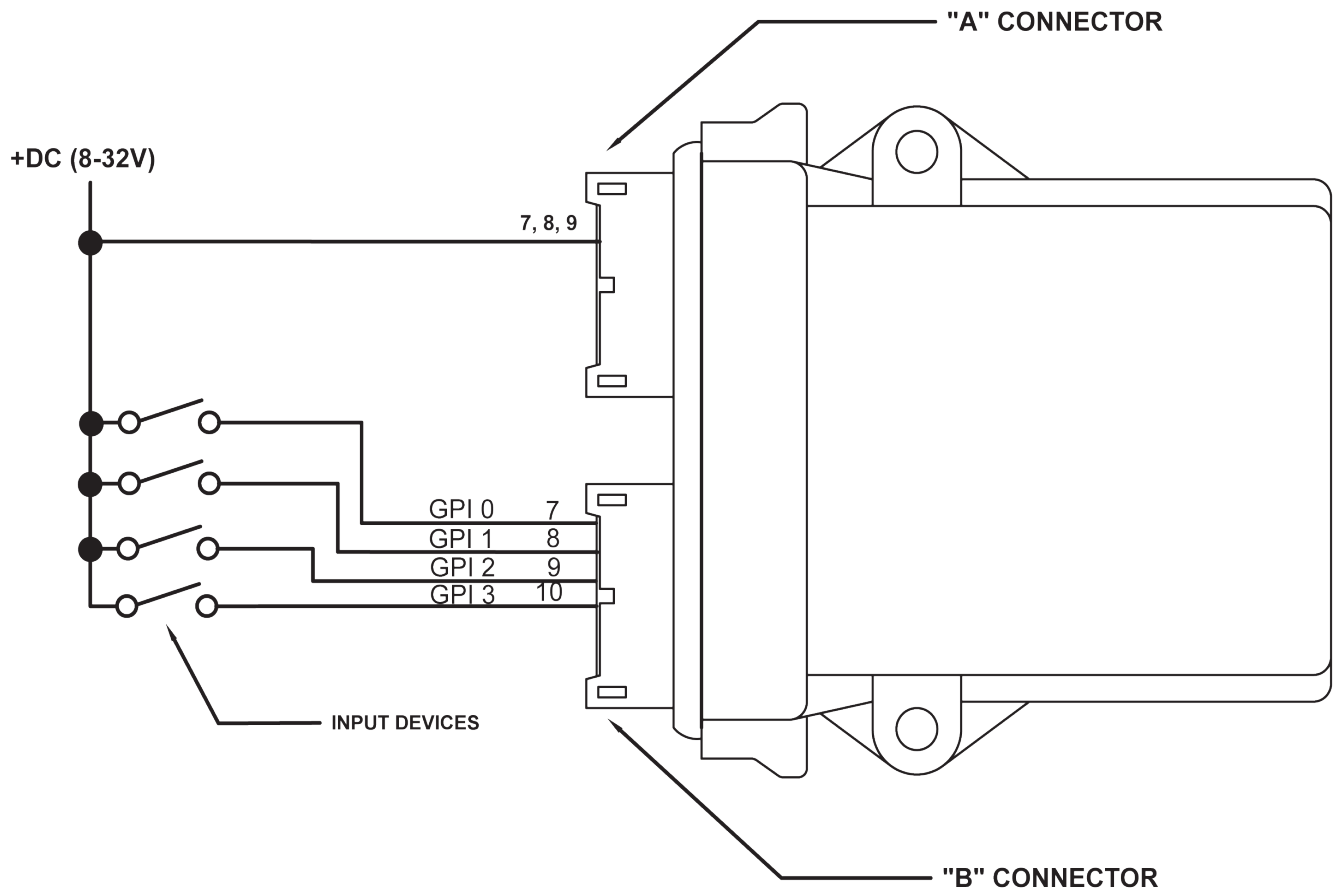

Figure 2.5 - Typical Digital Input Connections

Counter Inputs

As was noted in the Digital Inputs Section, two of the digital inputs (GPI0, GPI1) may be utilized as high speed counters (up counting only). These inputs will accept a maximum frequency of 40KHz and are optically isolated to promote noise immunity. These inputs are ideal to anywhere that high speed counting is required; such as calculating RPM, batch counting and more.

To use GPI0 or GPI1 in a ladder diagram as a high speed counter, you must use the CNTRMR function block. This block, when placed in the ladder diagram, will provide a drop-down menu to select which counter to use. Refer to the EZ LADDER Toolkit User's Manual for details on the CNTRTMR and other function blocks. GPI0 is Counter Channel 1 while GPI1 is Counter Channel 2 in the CNTRTMR function block.

Please note: Individually, the GPI0 and GPI1 inputs are designed to be used as a digital input only or high speed counter input only. EZ LADDER will allow the placement of contacts and /or CNTRTMR function in any program. Therefore, you can place and use the contacts and the CNTRTMR function block in the same program with the same digital input selected. This can be useful in some programs based on the application, but it is important to know that input contacts will only operate at a fraction of the frequency that the CNTRTMR function block can accurately read.

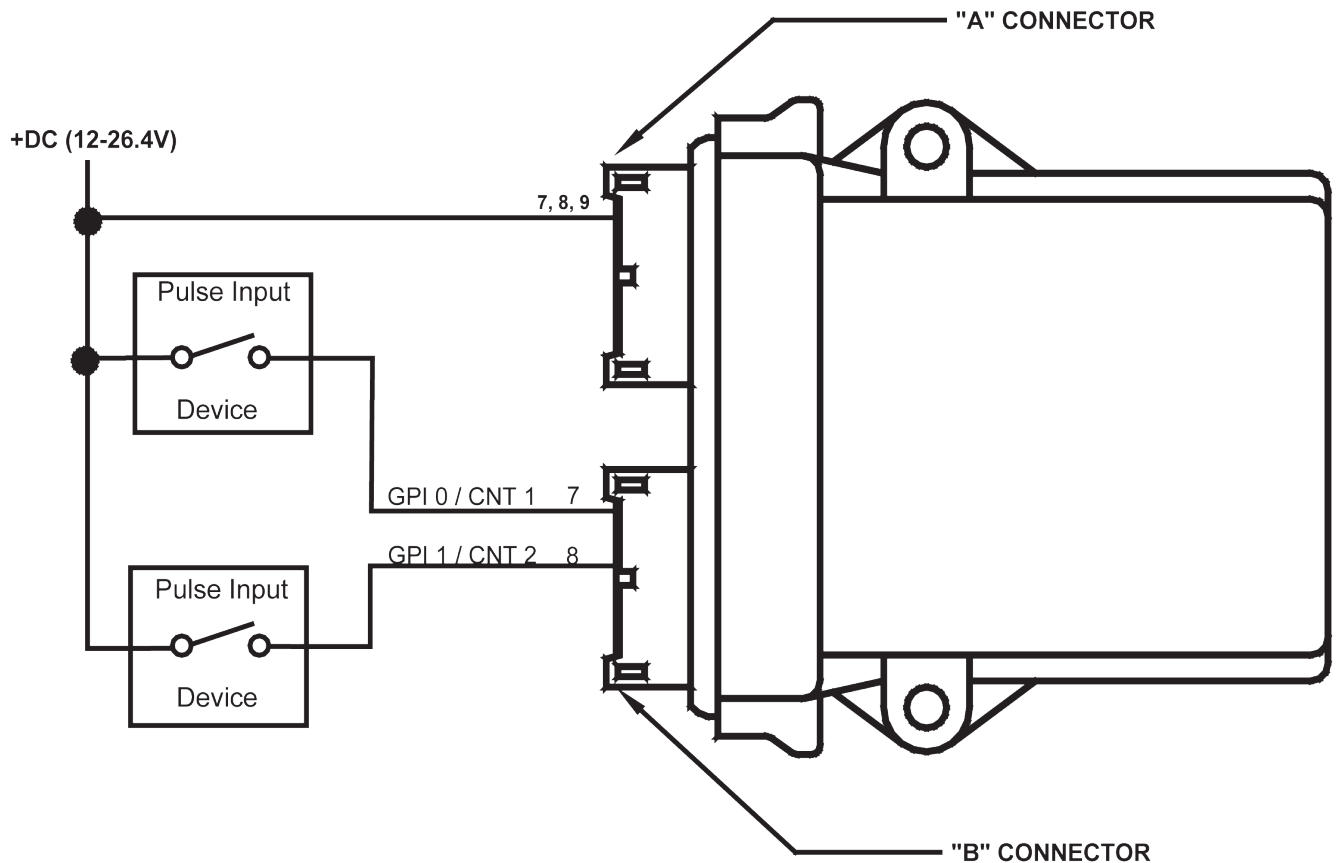Typical High Speed Counter connections are shown in Figure 2.6.

Figure 2.6 - Typical Counter Input Connections

Digital Outputs

The HEC-4xxx-E-R includes 6 on-board digital outputs. They are identified in the EZ LADDER Toolkit and this manual as GPO0 - GPO5. These outputs are sourcing, therefore an energized output will source an output voltage equal to the controller input voltage. Refer to Figure 2.7 for typical output connections.

Each output can drive a load up to maximum current rating listed in the specifications section (Refer to Figure 2-16 for current and temperature ratings) and includes an automatic over-current shutdown safety. In the event an over current condition exists, the output will shut down. This shut down condition is reset when the output is turned off (set to false) in the ladder diagram.

Each output requires a minimum load to operate correctly. Depending upon the device connected to an output, a minimum load resistor may be required. If the output is ON or true regardless of the ladder diagram program, connect a 470Ω to 1KΩ load from the output to input power common.

Each digital output (GPO0 - GPO3) may be configured and used as a digital output or as a Pulse Width Modulation (PWM). Each of these four outputs may only be used as either digital output or PWM output only. For information on using digital outputs as PWM outputs, refer to the Pulse Width Modulation Outputs Section of this manual. GPO4 and GPO5 are digital outputs only and cannot be used as PWM channels.

Commutating diodes should be installed on all output channels for noise immunity. See Figure 2.7. If using current feedback, these diodes must be installed for the feedback reading to be correct.

To control a digital output in a ladder diagram, place and connect the appropriate coil for your needs. The DIRECT COIL and INVERTED COIL functions are used to control digital outputs in the ladder diagram. When placing the coil, verify you select the correct output address (GPO0 - GPO5) from the provided drop-down menu.

In addition to controlling the outputs, the status of each digital output may be *monitored* for an OK or Fault status. When the HEC-400x target is configured in EZ LADDER, 6 status variables are created automatically, identified (STAT0 - STAT6). These variables indicate the status of the output and may be used in the program as any boolean variable (DIRECT CONTACT or INVERTED CONTACT). A High or True condition indicates that the output is functioning properly while a Low or False condition indicates a fault condition of the output (open load or overload).

Additionally, GPO0 - GPO3 also have current sense feedback capability using analog inputs (AN4-AN7 respectively). These analog inputs can be utilized in the program as control parameters.
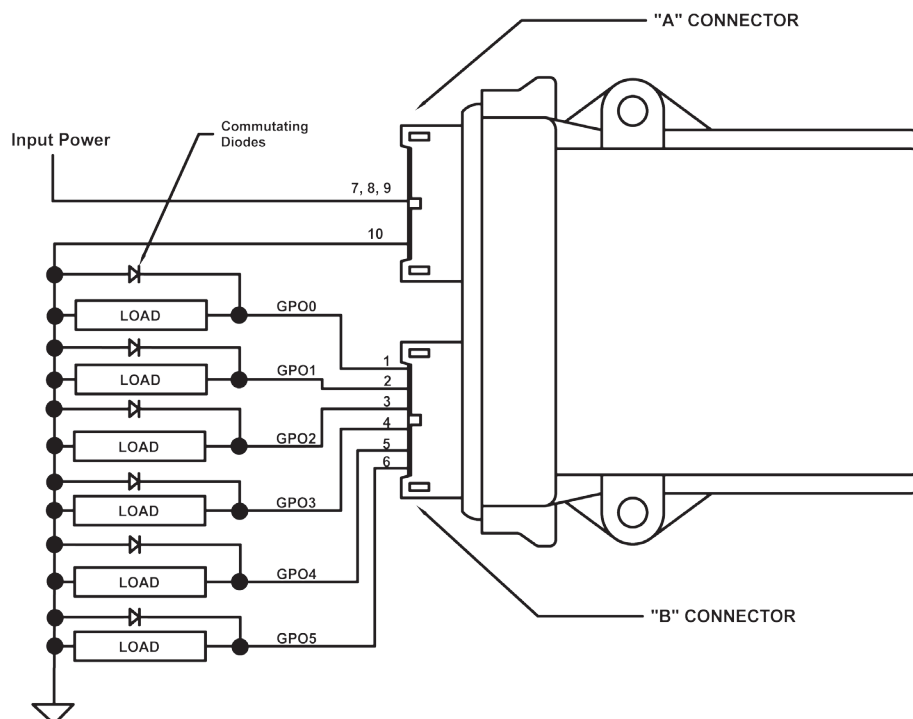

Figure 2.7 - Typical Digital Output Connections

Pulse Width Modulation Outputs

As previously noted, the HEC-4xxx-E-R includes 4 on-board digital outputs that may be configured individually and exclusively as either digital outputs or pulse width modulation outputs; therefore, each output may only be used as either digital output or PWM output.

Before Pulse Width Modulation outputs may be used in the ladder diagram, the Pulse Width Modulation Properties must be configured in EZ LADDER Toolkit.

To Configure Pulse Width Modulation (PWM) Outputs in EZ LADDER Toolkit:

1. In EZ LADDER, from the File Menu at the top, click **PROJECT** then **SETTINGS**. This will open the Project Settings Window. The HEC-4000 was previously selected.
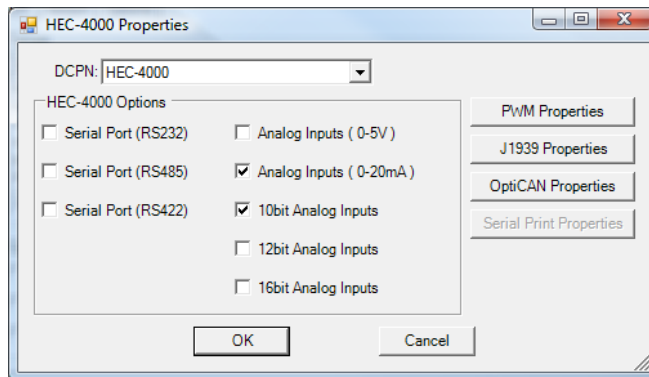2. Click the **PROPERTIES** button. The HEC-4000 Properties Window will open. Refer to Figure 2.8.

Figure 2.8 - HEC-4000 Properties Window

3. Click the **PWM PROPERTIES** button. The PWM Properties Window will open. Refer to Figure 2.9.
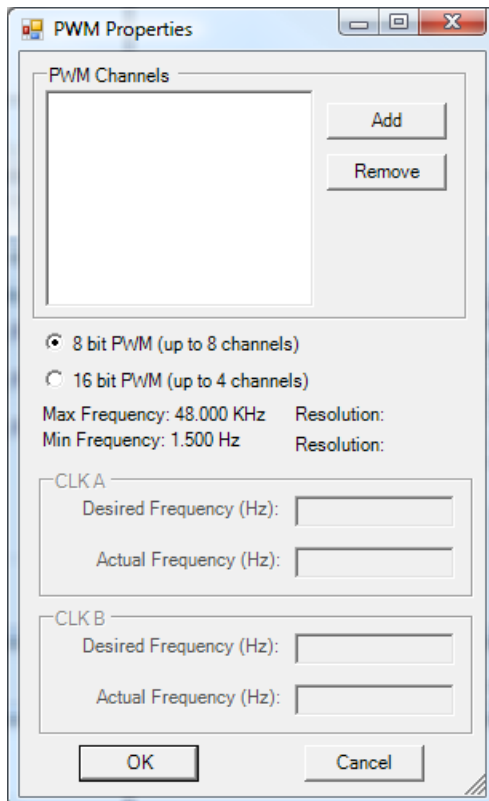

Figure 2.9 - PWM Properties Window

4. Select the resolution of the PWM channels (8 or 16 bit). Only 4 channels are supported regardless of resolution.
5. Click the **ADD** button in the PWM Properties window.
6. In the ADD PWM dialog, select the channels to install. To select multiple PWM channels, hold the CTRL key while clicking on the channel. Refer to Figure 2.10.

Only 4 PWM channels are supported, they are as follows:

Digital Output 0 - PWM 1   Digital Output 3 - PWM 5
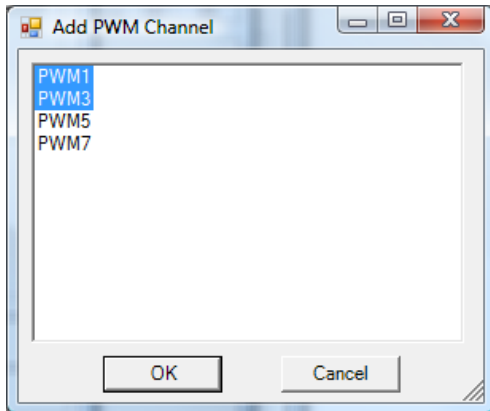Digital Output 1 - PWM 2   Digital Output 4 - PWM 7

Figure 2.10 - ADD PWM Window

6. Click **OK** to close the ADD PWM dialog. The next step is configuring the frequencies.

7. Enter the desired frequency for Clock A and Clock B (if installed). The HEC-4xxx-E-R has 4 available PWM Channels. These channels are either controlled with Clock A or Clock B. This allows two different PWM frequencies. The Minimum and Maximum frequencies are displayed in the PWM Properties dialog. The frequency for Clock A and Clock B must be in this range. Refer to Figure 2.9.

Due to limitations of hardware, the Desired Frequency and Actual Frequency may vary. The Actual Frequency will be the closest attainable frequency to the entered Desired Frequency. The Minimum and Maximum frequencies are displayed.

8. Click **OK** to close the PWM Properties Window. Click **OK** to close the HEC-4000 Properties Window and click **OK** to close the Project Settings Window.

With the Pulse Width Modulation Outputs configured in EZ LADDER, they can now be used in the ladder diagram project. The PWM channel(s) are controlled in the ladder diagram by the PWM and PWM_FREQ function blocks. For each PWM channel required, a PWM function block is required. Typically, PWM Outputs operate at a set frequency while the Duty Cycle is adjusted to vary the output. The Duty Cycle is a variable input to the PWM function block. In the event the frequency must be changed during operation, the PWM_FREQ function block is used. Refer to the EZ LADDER Toolkit User's Manual for more detail regarding function blocks and variables.

Refer to Figure 2.11 for PWM channel connections.

Commutating diodes should be installed on all PWM output channels for noise immunity. See Figure 2.11.
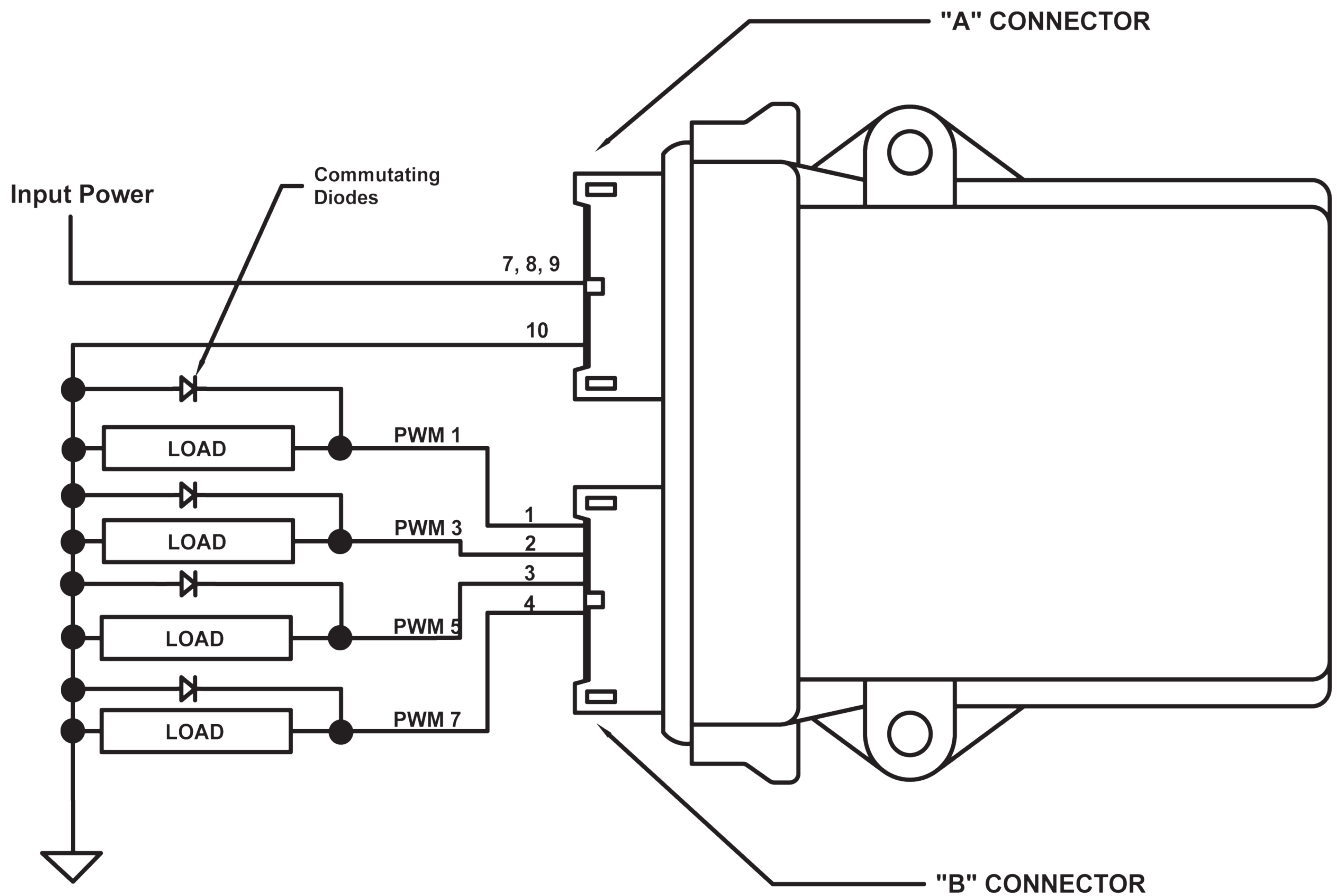
Figure 2.11 - Typical PWM Output Connections``

Analog Inputs

The HEC-4xxx-E-R provides 4 analog inputs for external devices. The resolution and rating for the analog inputs is model dependent. The HEC-4xxx-E-R is offered with 10 bit, 12 bit and 15 bit resolutions with ratings of either 0-5VDC or 0-20mADC. Each analog input is represented in the EZ LADDER Toolkit ladder diagram using variables labeled AN0 through AN3 respectively. These variables are created automatically when the HEC-4xxx-E-R target is selected in the Project Settings Window.

The following represents the part number, resolution, rating and the integer values for each HEC-4xxx model.

Model	Rating	Resolution	Min - Max Integer Value
HEC-400x-E-R	0-20mADC	10 bit	0 - 1023
HEC-401x-E-R	0-5VDC	10 bit	0 - 1023
HEC-410x-E-R	0-20mADC	12 bit	0 - 4095
HEC-411x-E-R	0-5VDC	12 bit	0 - 4095
HEC-420x-E-R	0-20mADC	15 bit	0 - 32767
HEC-421x-E-R	0-5VDC	15 bit	0 - 32767

Each variable (AN0 - AN3) will represent the actual current reading on the analog input as an integer number (see range above). To use the analog input reading, place the appropriate analog input variable as an input to function blocks.

Figure 2.12A shows the typical connections for using the analog inputs. Figure 2.12B illustrates the typical internal analog input circuit.
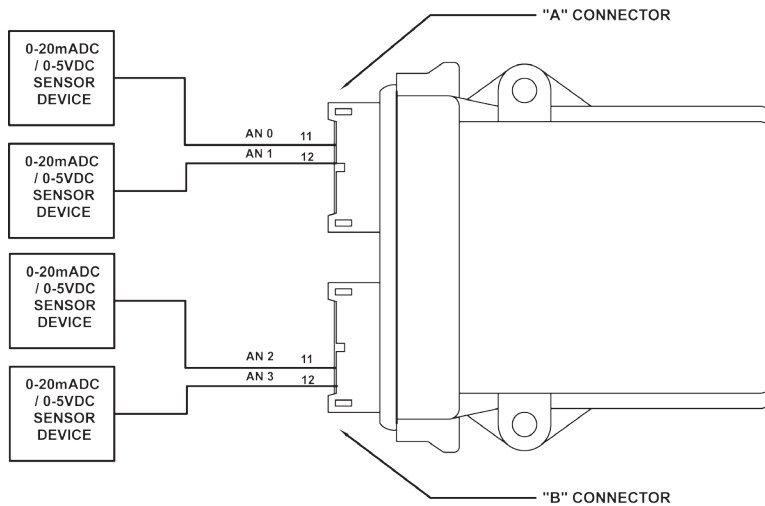
Figure 2.12A - Typical Analog Input Connections

* The 249 Ohm resistor shown is installed on 0-20mA models, not installed on 0-5VDC Models.
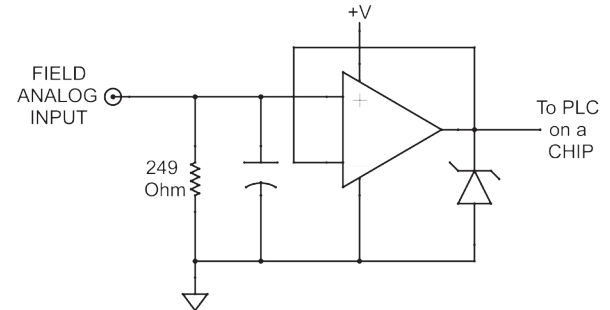
Figure 2.12B - Typical Analog Input Circuit

Output Current Feedback

The HEC-4xxx-E-R provides current feedback for each PWM capable output (GPO0 - GPO3). Each of these four outputs are internally monitored using analog inputs (AN4-AN7 respectively). This analog feedback represents the output current from 0 to 4 Amps.

As with all other analog inputs, these variables are created automatically when the HEC-4xxx-E-R target is selected and configured. The resolution of these feedback analog input channels is dependent upon the model number of the HEC-4xxx as described in the Analog Inputs Section (10 bit, 12 bit or 16 bit). These channels will always be the same resolution as the external analog input channels (AN0 - AN3).

These analog inputs may be used in combination with function blocks in circuits to calculate the actual output current on the PWM channel.

Commutating diodes must be installed on PWM channels when using the current feedback analog inputs. Failure to use commutating diodes will result in incorrect current feedback readings. See Figure 2.11.

General Purpose Serial Port - Models HEC-4xx1-4xx3-E-R

The HEC-4xxx-E-R (HEC-4xx1-E-R, HEC-4xx2-E-R, HEC-4xx3-E-R) optionally may be ordered with a second serial port. This serial port is a general purpose serial port that supports serial printing. This port may also be used to communicate to a Modbus Master Device (the HEC is a Modbus Slave). At this time, the general purpose serial port is an output device only as there is no software support to read a serial input.

This port may be factory ordered as HEC-4xx1-E-R (RS232), HEC-4xx2-E-R (RS422) or HEC-4xx3-E-R (RS485). The general purpose serial port connection is achieved by a factory installed cable with an industry standard M8 connector. The HEC-4xx0-E-R does not have a general purpose serial port. Figure 2.13 illustrates the general purpose serial port cabling. For cable pin assignments, refer to Figure 2.14A.
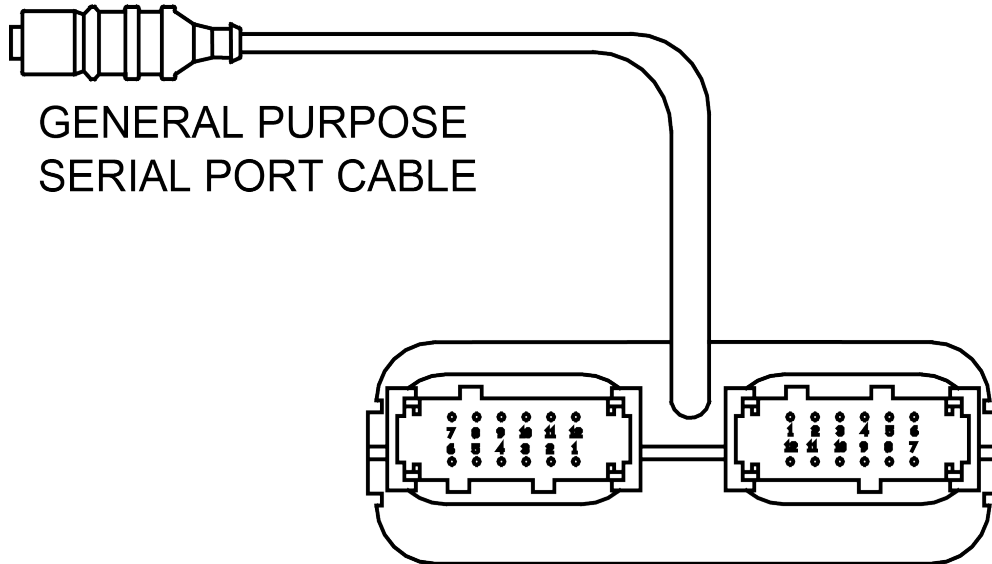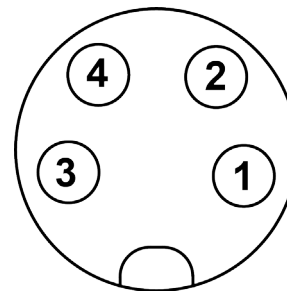
GENERAL PURPOSE
SERIAL PORT CABLE

Figure 2.13- General Purpose Serial Port

```
RS232 Serial Port - HEC-4xx1-E-R

Pin      ID       Description
1        RX       Receive Data
2        TX       Transmit Data
3        GND      Ground
4        RTS      Request to Send
```

```
RS485 Serial Port - HEC-4xx3-E-R

Pin      ID       Description
1        TX+      Data (+)
2        TX-      Data (-)
3        GND      Ground
4        --       No Connect
```

```
RS422 Serial Port -HEC-4xx2-E-R

Pin      ID       Description
1        RX-      Receive Data (-)
2        RX+      Receive Data (+)
3        TX+      Transmit Data (+)
4        TX-      Transmit Data (-)
```


A connector cover for General Purpose serial port is available. Order using Divelbiss Part # 120-106189

Figure 2.14A - General Purpose Port Pin Assignments: HEC-4XX1-E-R to HEC-4XX3-E-R

General Purpose Serial Port - Models HEC-4xx4-E-R

The HEC-4xx4-E-R includes a factory installed field selectable RS232/RS422/RS485 serial port. This serial port is a general purpose serial port that supports serial printing. This port may also be used to communicate to a Modbus Master Device (the HEC is a Modbus Slave). At this time, the general purpose serial port is an output device only as there is no software support to read a serial input.
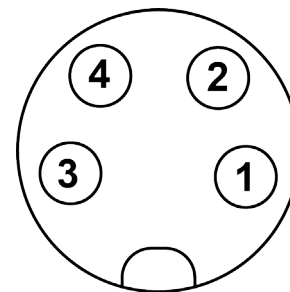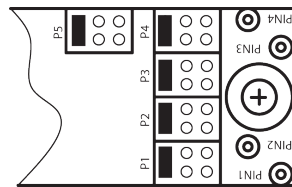
The general purpose serial port connection is achieved by a factory installed cable with an industry standard M8 connector. Figure 2.13 illustrates the general purpose serial port cabling. For cable pin assignments, refer to Figure 2.14B.

Based on the need of RS232, RS422 or RS485, the 4 pin M-8 cable assembly will differ. Follow the pin-outs for the type of interface required. Next, using the jumper assignments, configure the jumpers for either RS232, RS422 or RS485. The only remaining item is setting the type in EZ LADDER (Mobus or Serial Printing settings).

To configure the jumpers, it will be necessary to dis-assemble the HEC-4000 series controller. See Dis-Assembling the HEC-4XXX-E-R Controller section.
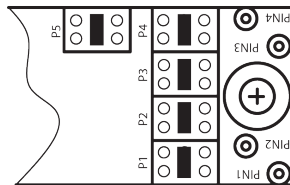
RS232 Serial Port - HEC-4xx4-E-R

Pin	ID	Description
1	RX	Receive Data
2	TX	Transmit Data
3	GND	Ground
4	RTS	Request to Send

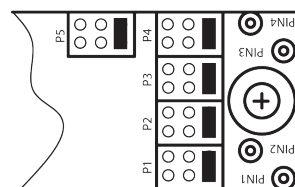A connector cover for General Purpose serial port is available. Order using Divelbiss Part # 120-106189

RS485 Serial Port - HEC-4xx4-E-R

Pin	ID	Description
1	TX+	Data (+)
2	TX-	Data (-)
3	GND	Ground
4	--	No Connect

Serial Configuration Jumpers

RS422 Serial Port -HEC-4xx4-E-R

Pin	ID	Description
1	TX+	Transmit Data (+)
2	TX-	Transmit Data (-)
3	RX+	Receive Data (+)
4	RX-	Receive Data (-)
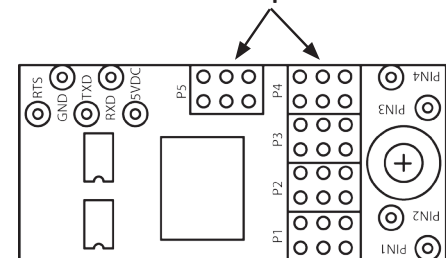
Internal Serial Board

Figure 2.14B - General Purpose Port Pin Assignments: HEC-4XX4-E-R

CAN Networking Ports

The HEC-4xxx-E-R provides two on-board CAN bus interface ports. These CAN ports may be used for additional communications and networking including SAE J1939 and the Divelbiss proprietary OptiCAN Network.

The on-board CAN ports are CAN 0 and CAN 4 respectively. To use the HEC's CAN ports as either SAE J1939 or OptiCAN, it will be necessary to configure certain parameters. These parameters may be configured from the HEC-4xxx Properties Window in the Project Settings. As these settings vary greatly and are software based only, please refer to the EZ LADDER Toolkit User's Manual for details on configuring, using and implementing CAN port networking including all relevant function blocks.

The CAN ports should be wired according to established practices for CAN networks. Figure 2.15 illustrates typical CAN Port connections.
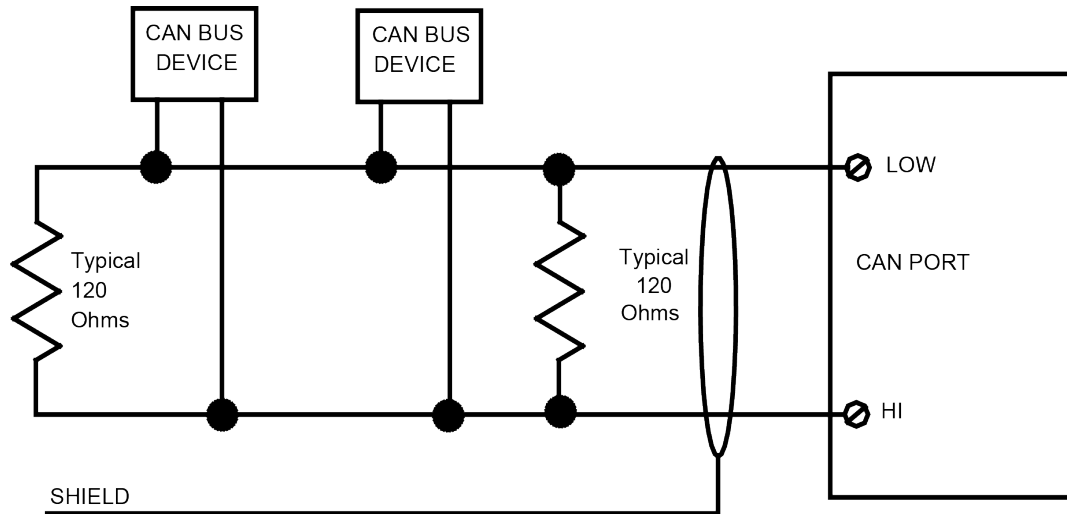
Figure 2.15 - Typical CAN Port Connections

HEC-4xxx-E-R Target Setting Options

To use some of the function blocks and features on the HEC-4xxx-E-R, it may be required to configure additional target properties in the Project Settings Dialog Box. Click **PROJECT** then **SETTINGS**. With the **HEC-4000** selected, click **PROPERTIES**.

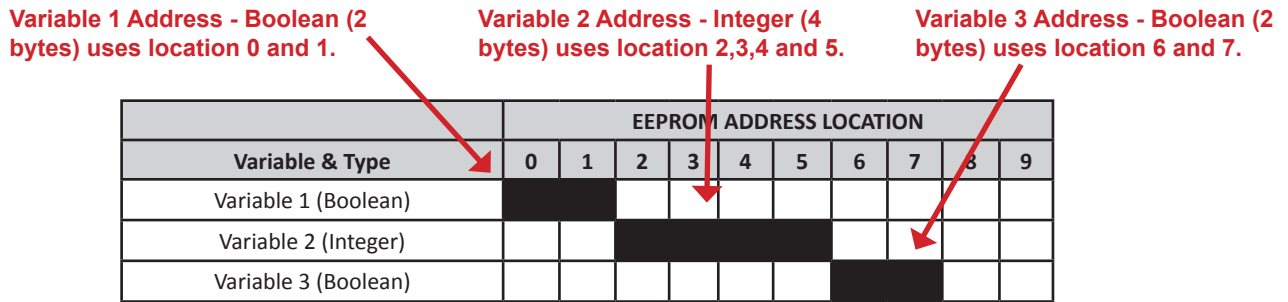The following are items that must be configured in the HEC-1000 Project Settings, Properties Dialog.

PWM Properties   This is used to configure the Pulse Width Modulation channels (see *Pulse Width Modulation Outputs*).

J1939 Properties   This is where SAE J1939 Communications is enabled and configured. Refer to the J1939 section of the EZ LADDER Manual.

OptiCAN Properties   This is where OptiCAN Communications is enabled and configured. Refer to the OptiCAN section of the EZ LADDER Manual.

Serial Print Properties   This is used if the Serial Print function block is to be used to transmit data to an external device using the General Purpose Serial port. The serial port is configured here.

EEPROM Memory

As one of the standard features of PLC on a Chip™ and EZ LADDER Toolkit, the HEC-4XXX supports the use EEPROM memory that may be used to store and recall boolean, integer, real and timer values in non-volatile memory in the ladder diagram. This can be used to store field adjustable set points and more.

The HEC-4XXX supports 2792 bytes of EEPROM memory. This memory is accessed in the ladder diagram using the EEPROM_READ and EEPROM_WRITE Function blocks. The same variable type that writes to the EEPROM location should be used to read the EEPROM location. A memory map is recommended for organizing variables stored in EEPROM.

Each EEPROM address is absolute and is one byte in size. Boolean variables fill two bytes while all other variable types fill four bytes of EEPROM. When writing a boolean to address 0, the actual variable will use addresses 0 and 1 (two bytes). Should you write an integer variable into address 0, then it would use addresses 0-3. A memory map should be created and used to assign variable types and addresses prior to coding to ensure that variable size and types are accounted for.

Variable 1 Address - Boolean (2 bytes) uses location 0 and 1.

Variable 2 Address - Integer (4 bytes) uses location 2,3,4 and 5.

Variable 3 Address - Boolean (2 bytes) uses location 6 and 7.

Variable & Type	EEPROM ADDRESS LOCATION									
	0	1	2	3	4	5	6	7	8	9
Variable 1 (Boolean)	■	■								
Variable 2 (Integer)			■	■	■	■				
Variable 3 (Boolean)							■	■		

Figure 2.16 - EEPROM Memory Locations

EEPROM storage area has a limited number of write cycles; therefore it shouldn't be used to store data which changes often and must be re-written often. Writing often to the same location can cause the location to fail.

Specifications

Processor:	PLC on a Chip™
Memory:	256K Flash, 12K RAM, 2792 Bytes EEPROM
Serial Ports:	1 Programming Port (Max baud: 57.6K);
	1 Multipurpose Port, Factory Configured as RS232, RS422 or RS485 (4XX1 to 4XX3 Models)
	1 Multipurpose Port, Field Selectable as RS232, RS422 or RS485 (4XX4 Models)
Networking:	2 CAN Ports for Divelbiss OptiCAN and J1939 Communications, Modbus Slave on Models with Optional Serial Port
Digital I/O:	4 Inputs & 6 Outputs on-board, Expandable using OptiCAN Network
	Inputs rated 8-32VDC
	Outputs rated 4A Max [SEE NOTE 1], Over-current protected. Output Voltage = Input Power
Counters:	2 Channels, Count Up, 40KHz Max. (using Digital Inputs 0 and 1)
Analog Inputs:	4 Channels, 0-5VDC, 0-20mADC, 10 bit, 12 bit, 15 bit Resolution - all model dependent
PWM Outputs:	4 Channels 1.5 Hz to 1.0 KHz (using Digital Outputs 0-3), 4ADC Maximum - See Note 1
	Includes 4 analog input Output Feedback Channels (1 for each channel).
Input Power:	8-32VDC
Operating Temp:	-40-80° C [SEE NOTE 2]
Program Language:	Ladder Logic using Divelbiss EZ LADDER Toolkit.
Dimensions:	4.63" Wide x 5.24" Length x 1.43" Tall.
Mounting:	Panel Mount using screws
Type:	Enclosed, Sealed Plastic Housing
Storage Temperature:	-40-85°C
RoHS Compliant:	Yes

NOTE 1:   4ADC Total @ up to 50° C Maximum per 2 Output Channels. Channels paired as GPO0 / GPO1, GPO2 / GPO3, and GPO4 / GPO5.   Total Current is sum of both paired output channels. See Figure 2.17 for maximum output current per output channel pair based on ambient temperature.

NOTE 2:   Operating Temperature is -40-80°C temperature rating for models without optional serial port (HEC-4XX0). For models with optional serial port, the standard operating temperature is -25 - 80°C.   Full temperature range is available for serial port models., consult factory for delivery and price.
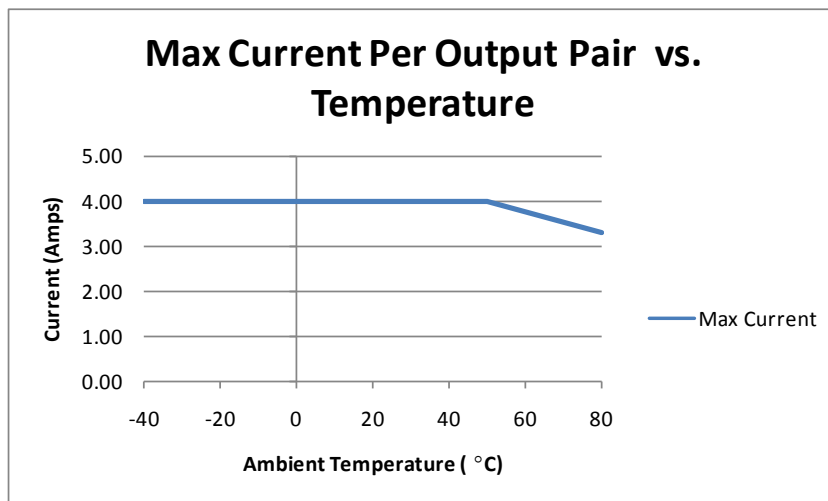

Figure 2.17 - Max Current for Outputs